

# Load Scheduling of Simple Temporal Networks Under Dynamic Resource Pricing

T. K. Satish Kumar, Zhi Wang, Anoop Kumar, Craig Rogers, Craig Knoblock

Information Sciences Institute, University of Southern California

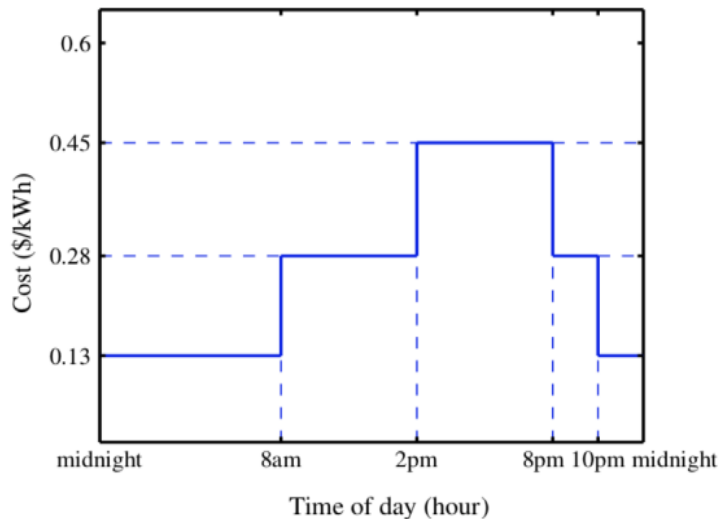
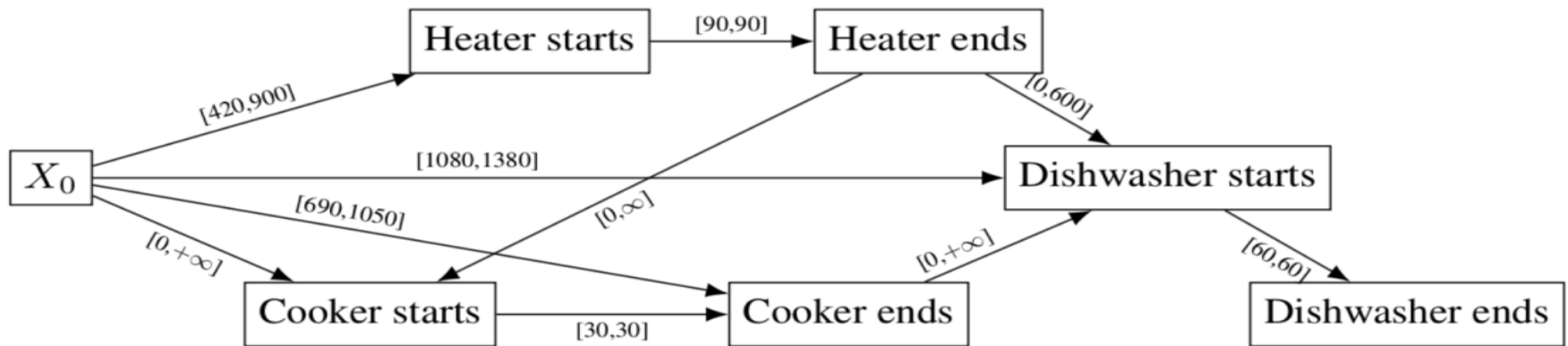


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# Executive Summary in Keywords

- *Simple Temporal Networks (STNs)*: temporal constraints between processes in scheduling problems.
- *Resources*: like electricity, consumed by processes.
- *Dynamic Price*: unit cost of electricity varies with time and total demand.
- *Polynomial-time Algorithms*: for cost minimization and optimal tradeoff against makespan in many important classes of such scheduling problems.

# Example: Smart Home

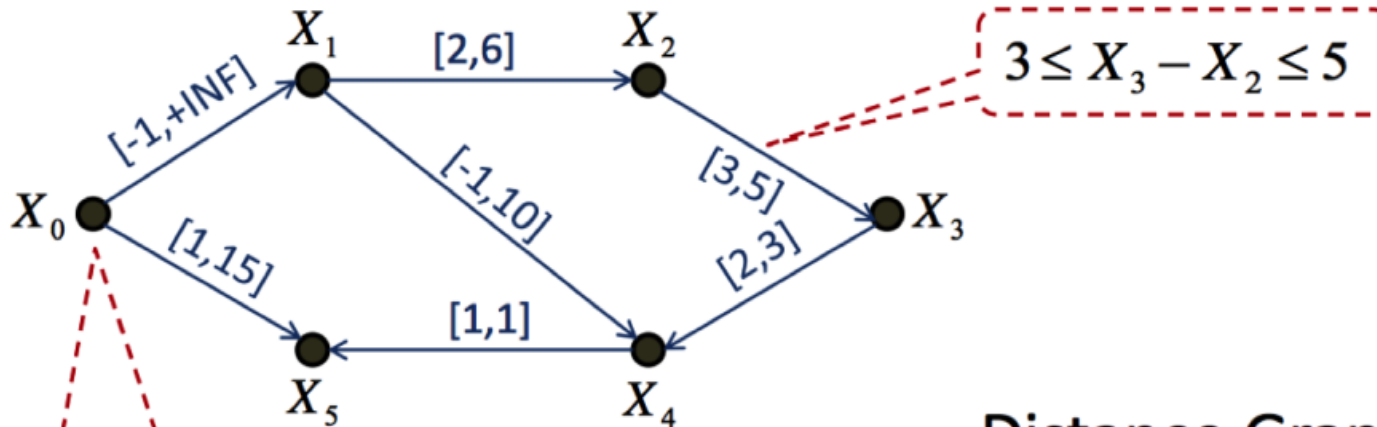


**Find a consistent schedule of minimum total cost.**

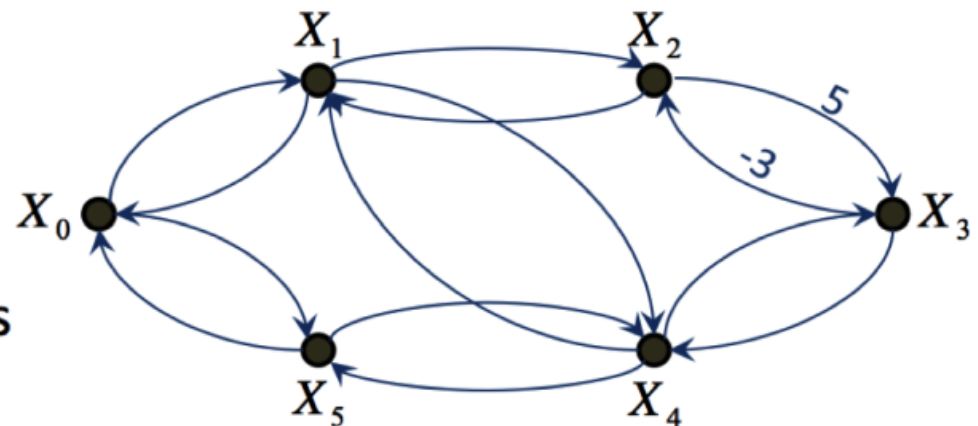
# Two Models of Resource Consumption

- **Model A:** Each process  $P_i$  consumes electricity at the rate of  $w_i$  watts during execution.
- **Model B:** Each process  $P_i$  demands its entire energy requirement, that is, the total energy  $W_i = w_i \text{duration}(P_i)$  at the beginning of its execution.
- Solving **Model B** is a little simpler. It also provides the critical combinatorial arguments useful for solving **Model A**.

# Simple Temporal Networks/Problems

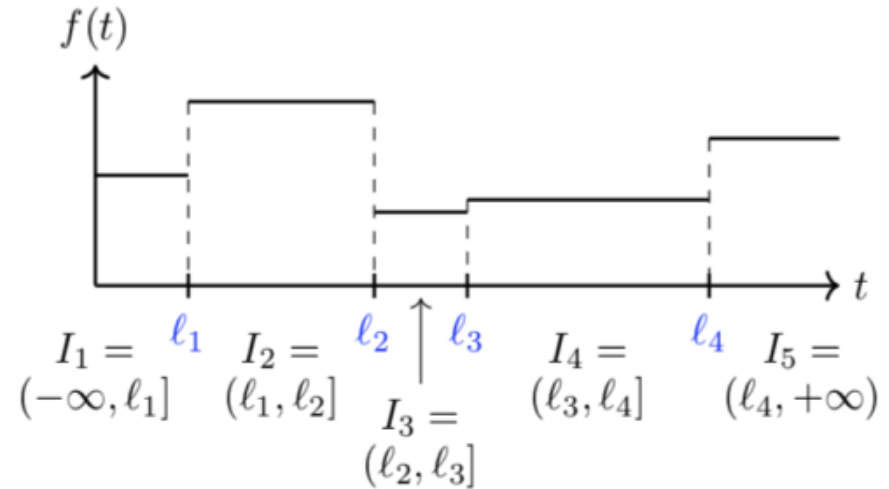
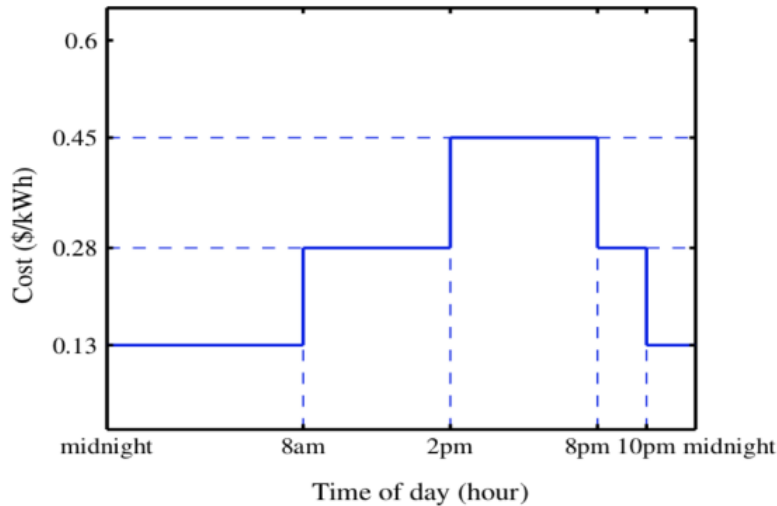


Distance Graph



STPs can be solved by shortest-path computations on their distance graphs

# Core Combinatorial Problem



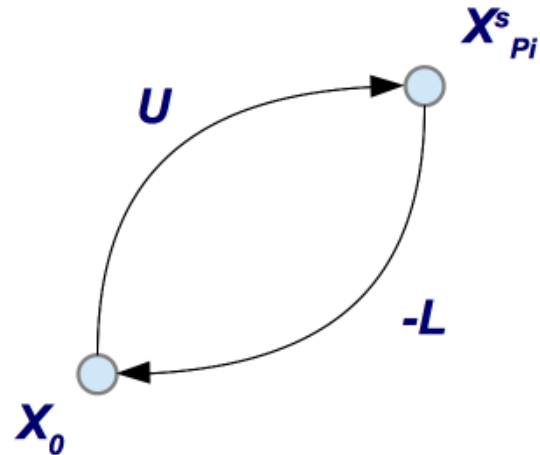
Each process  $P_i$  has to be *activated* in some interval  $I_j$ , that is, the starting point of  $P_i$  should be in  $I_j$ .

The cost for activating  $P_i$  in the interval  $I_j$  is  $W_i f(I_j)$ .

Find the best combination of intervals in which each process should be activated such that: (a) the schedule is consistent; and (b) the total cost is minimized.

# Activating Process $P_i$ in Interval $I_j$

- The beginning point of  $P_i$ , i.e.,  $X_{Pi}^s$ , should be scheduled after the left endpoint of  $I_j$  (say,  $L$ ) and before the right endpoint of  $I_j$  (say,  $U$ ).
- $X_{Pi}^s - X_0 \geq L$  and  $X_{Pi}^s - X_0 \leq U$ .

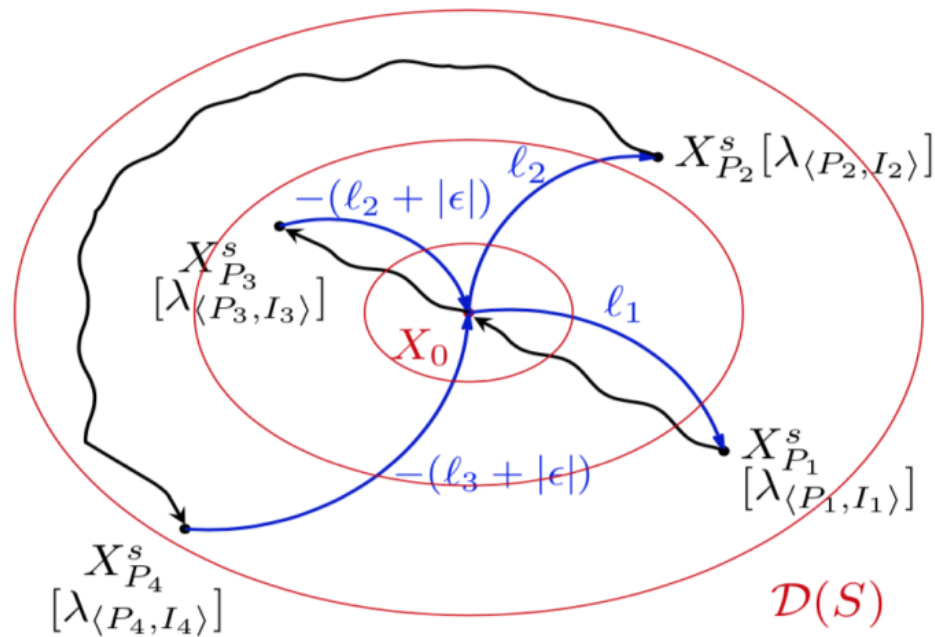


# Conflicts and Minimal Conflicts

- A *conflict* is a set of activations  $(P_1, I_{j1}), (P_2, I_{j2}) \dots (P_K, I_{jK})$  that cannot be simultaneously achieved.
- A *minimal conflict* is a conflict no proper subset of which is also a conflict.
- A set of activations  $(P_1, I_{j1}), (P_2, I_{j2}) \dots (P_K, I_{jK})$  can be simultaneously achieved if and only if they do not contain a minimal conflict.

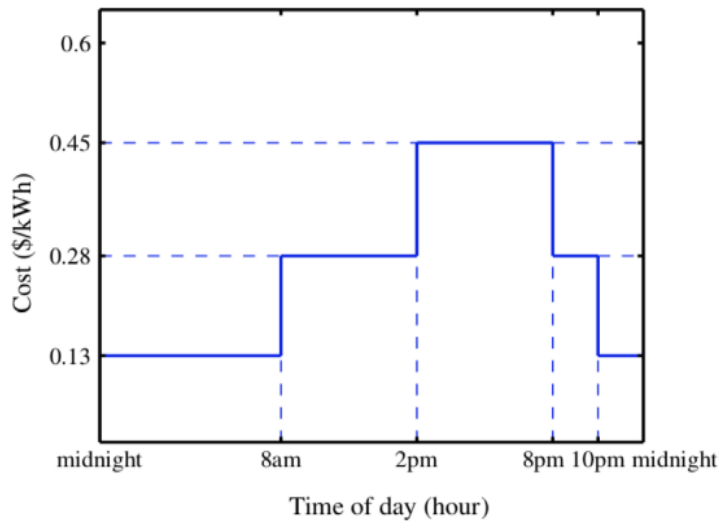
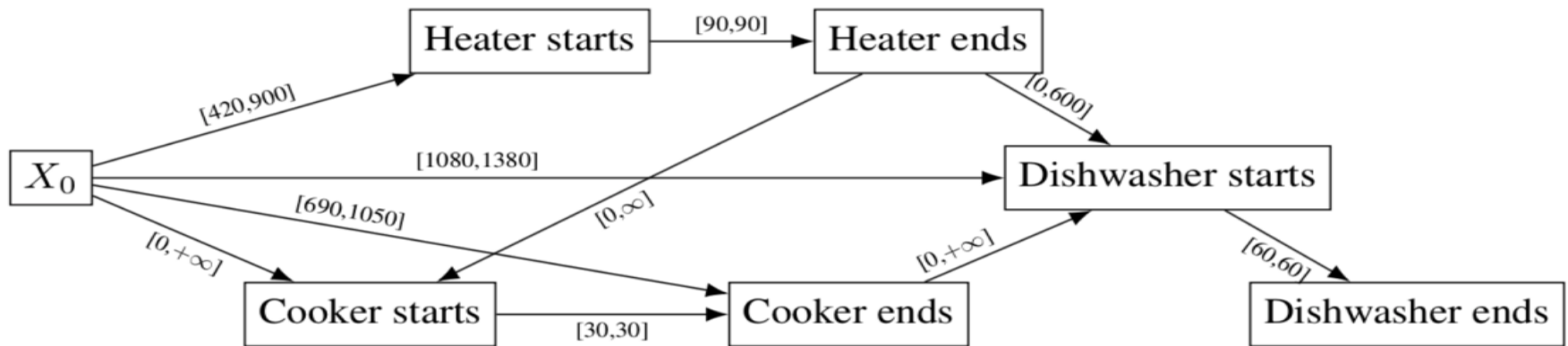


# Bounded Minimal Conflicts



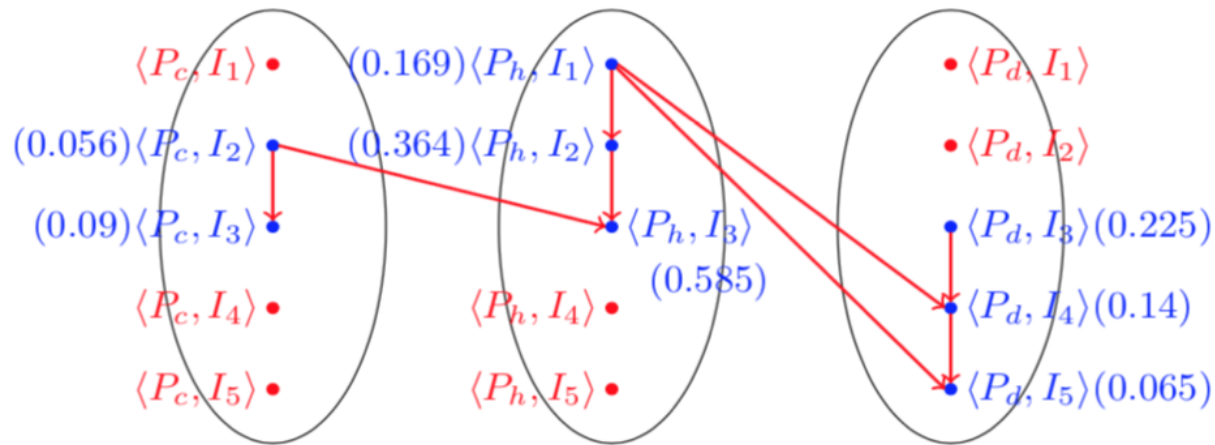
**The size of a minimal conflict is  $\leq 2$ .**

# Example: Smart Home



**Find a consistent schedule of minimum total cost.**

# Conflict Graph

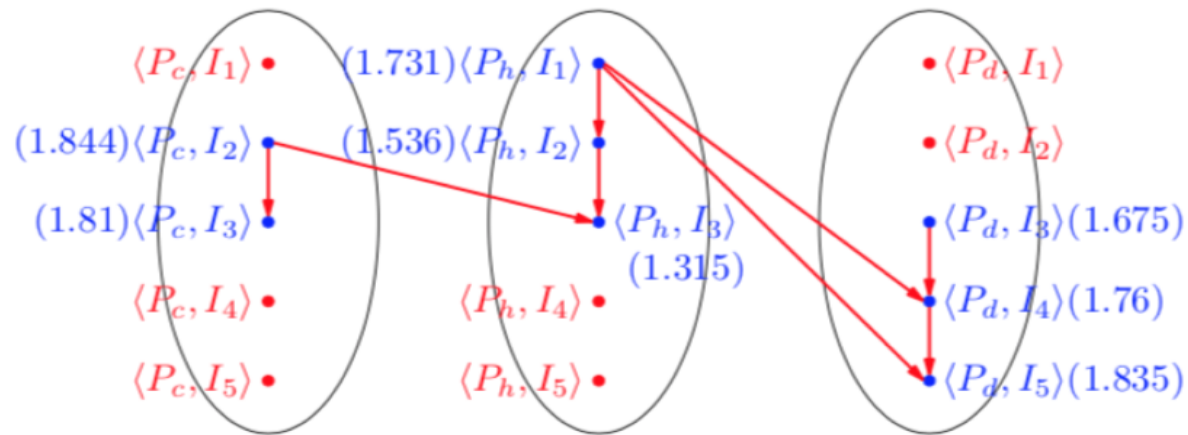


The *minimum weighted independent set* that includes *exactly one* interval activation for each process corresponds to the optimal solution.

**Issue 1:** Different from the maximum weighted independent set.

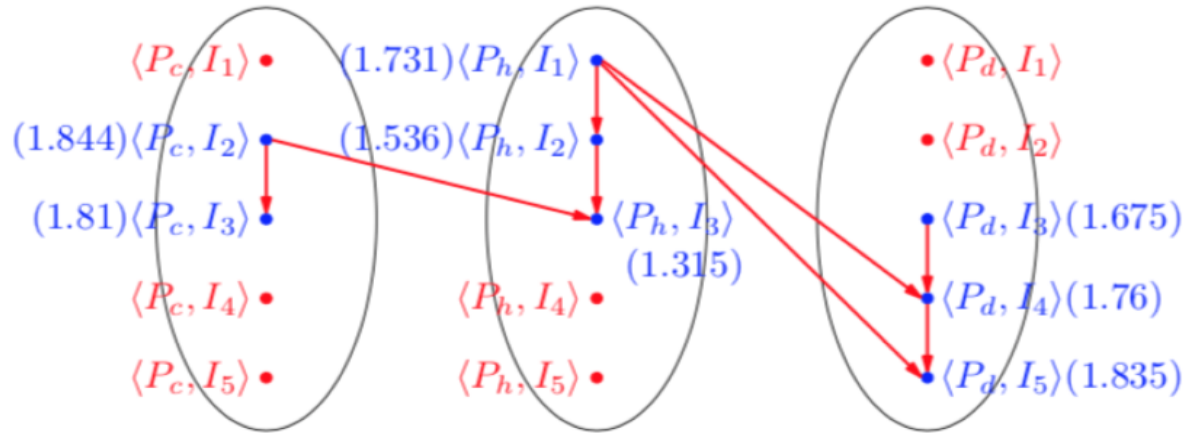
**Issue 2:** Computing the maximum weighted independent set is NP-hard.

# Solving Issue 1



A simple readjustment of weights converts the problem to a regular *maximum weighted independent set* problem.

# Solving Issue 2



The directed graph is a POSET, that is, it is acyclic and transitive.

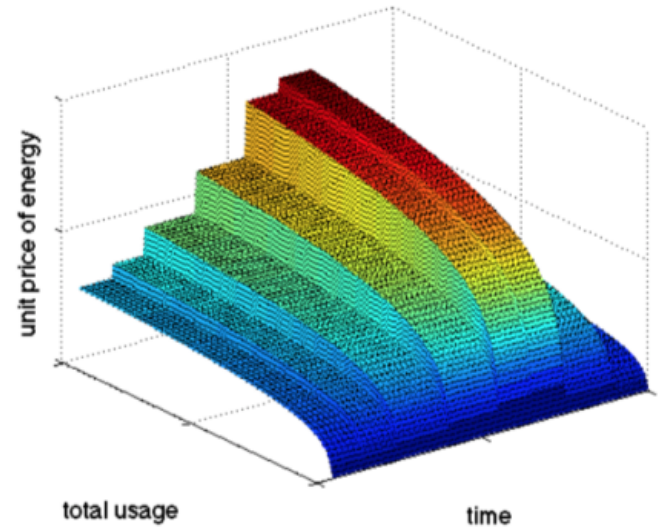
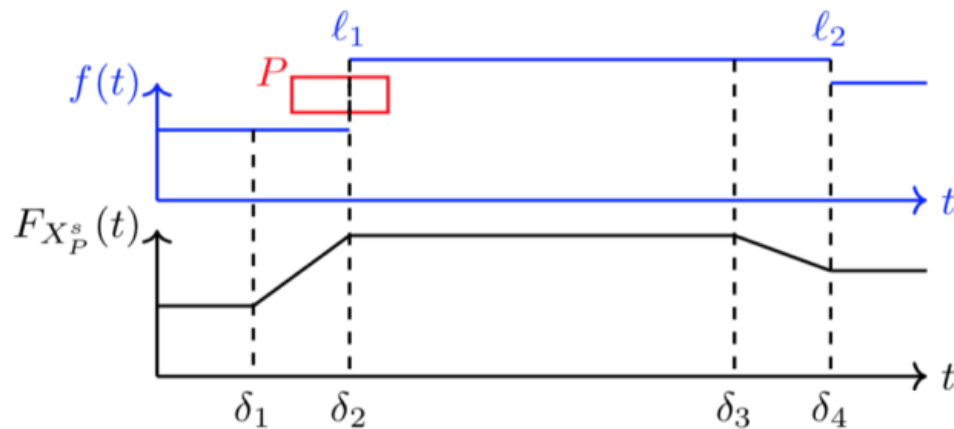
The maximum weighted independent set is the *maximum weighted antichain* in a POSET.

The maximum weighted antichain can be computed in polynomial time using a maxflow algorithm.

# Tradeoff Against Makespan

- Find a schedule that is of minimum makespan among all schedules with cost  $\leq \gamma$  optimal cost.
  - $\gamma$  is a given suboptimality factor  $\geq 1$ .
- **Key Observation:** makespan constraints are also simple temporal.
  - Do a Binary Search on makespan in the outer loop.
  - Solve the minimization of cost problem in the inner loop.
- Optimizations lead to Quasi Binary Search.

# Conjectured Tractable Classes and Negative Results



Conjectured to be tractable for **Model A** and for *concave* dependency of unit price on total demand.

But provably NP-hard for *convex* dependency of unit price on total demand.

# Conclusions and Future Work

- We presented a polynomial-time maxflow-based algorithm for optimally scheduling STNs with dynamic resource pricing.
  - Unit prices change with time but according to a piecewise constant function.
  - Processes demand energy requirements upfront.
- Conjectured tractable classes
  - Unit prices have a concave dependency on total demand.
  - Processes consume energy at a uniform wattage.
- Some NP-hard results
  - Unit prices have a convex dependency on total demand.
- **Future Work:** resolve conjectures; and apply algorithms to real-world engineering domains.